

# Preparing for the Final

## Dec 13, 4:00-6:00, ICS174

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ICS 271

Fall 2018

# Basics

- 2 hours
- closed-book
- 1 (one) sheet of A4 size paper of notes
- To pass MS comprehensive, must get at least B

# Material Covered

- Chapters 3-10
  - Search
  - Games
  - Constraint Satisfaction
  - Propositional Logic
  - First Order Logic
  - Classical Planning
- Only material we covered in class (lecture)

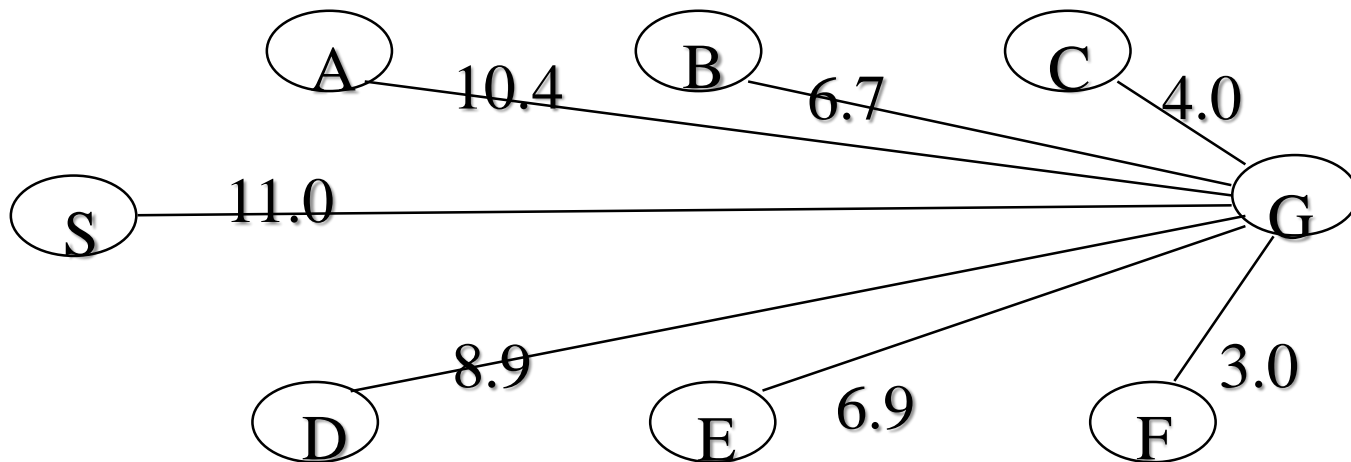
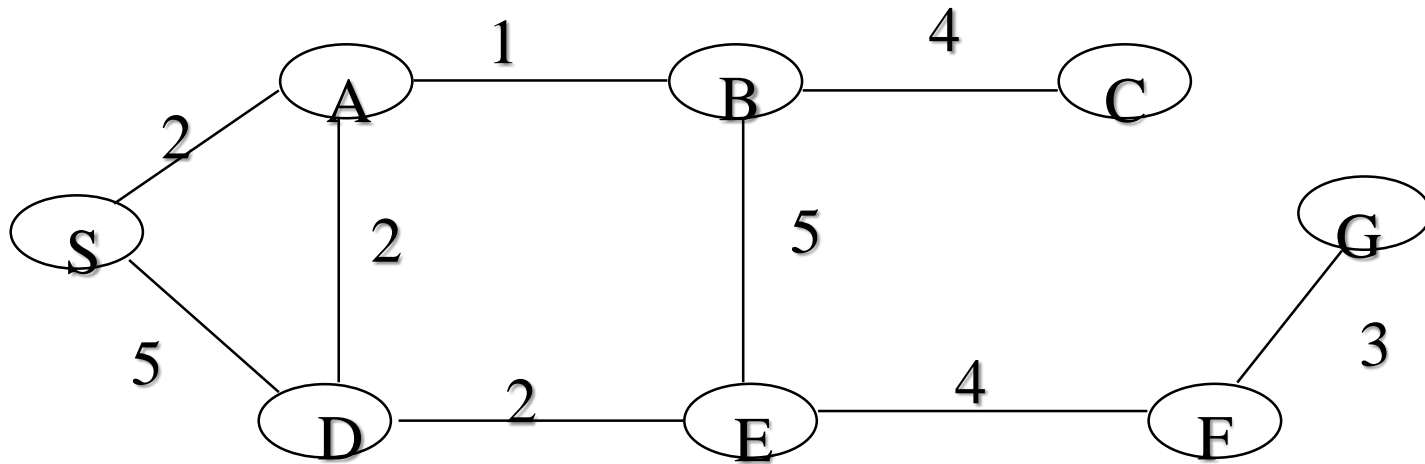
# Exam

- Section of TRUE/FALSE questions
  - e.g. “Arc consistent problem with non-empty variable domains is guaranteed to have a solution?”
- Sections
  - (Heuristic) Search
  - Games
  - Constraint Satisfaction
  - (First Order) Logic
  - Classical Planning

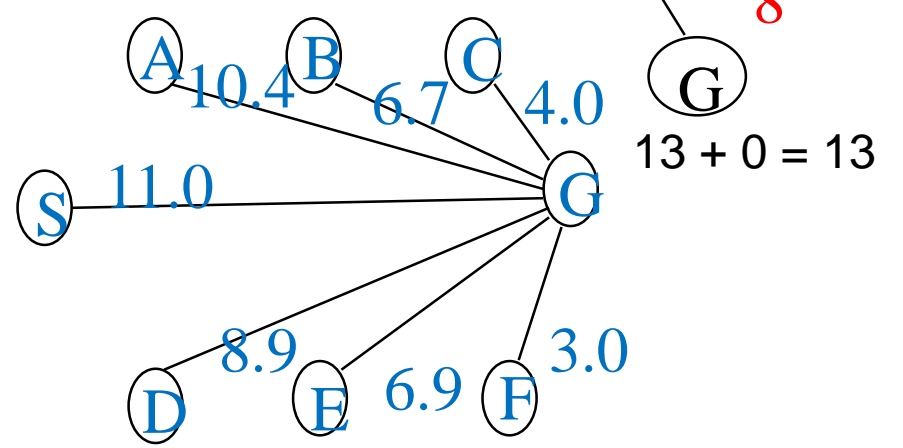
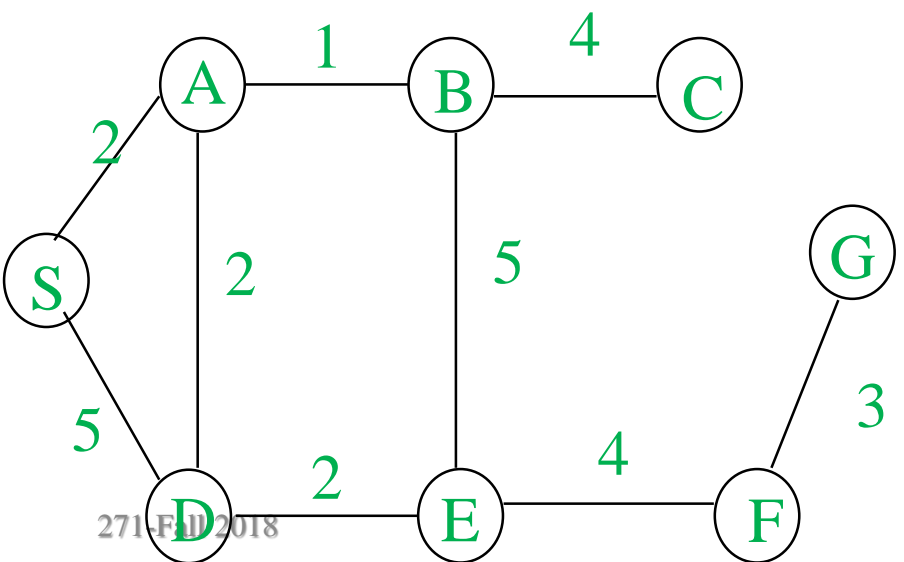
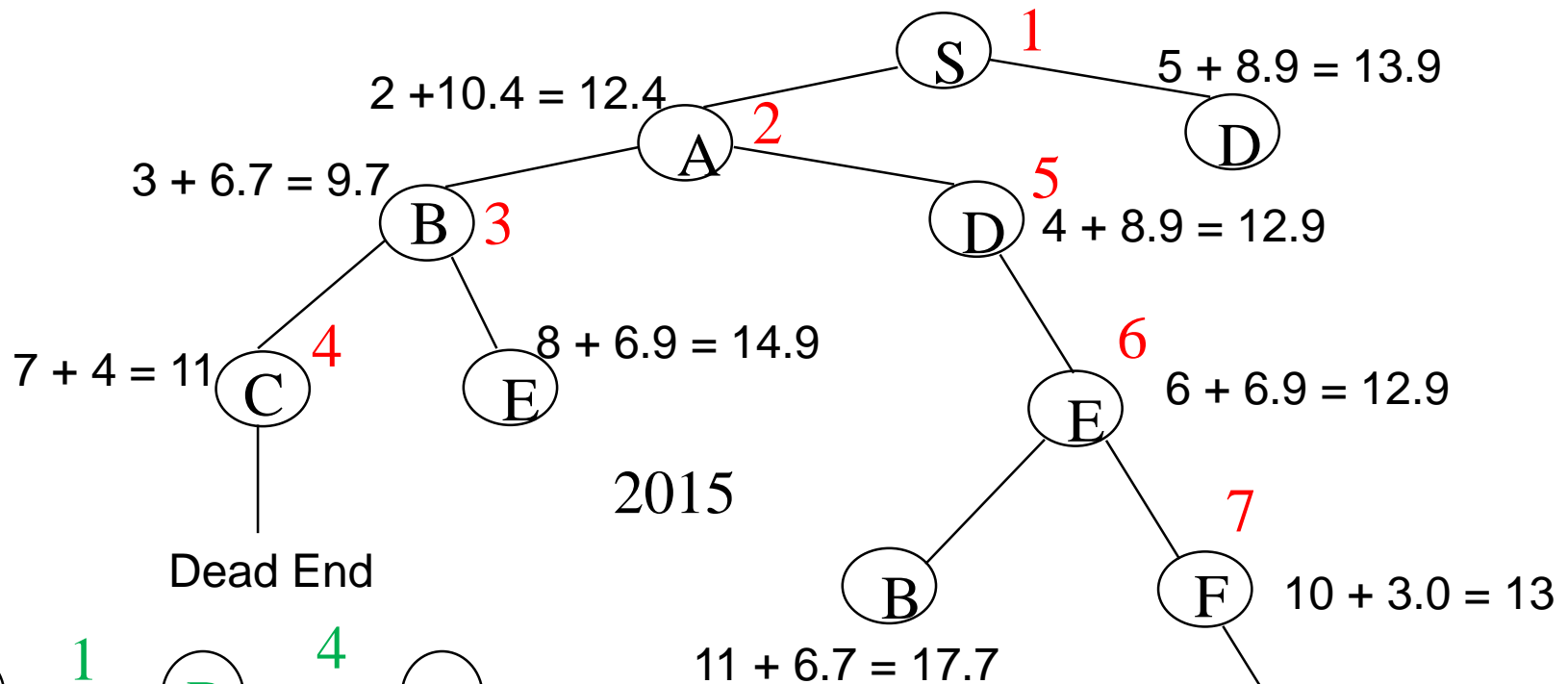
# Chapters 3,4 (Search) Concepts

- Search space : states (initial, goal), actions
- Search tree/graph
- Breadth-first, depth-first, uniform-cost search
  - Expanding a node, open (frontier), closed (explored) lists
  - Optimality, complexity
  - Depth limited search, iterative deepening search
- Heuristic search
  - Heuristic fn, admissibility, consistency
  - $f, h, g, h^*, g^*, C^*$
  - Heuristic dominance
- Greedy search
- A\*, IDA\*
- Branch-and-Bound DFS
- Generating heuristics from relaxed problems
- Hill-climbing search, SLS, local vs. global maxima

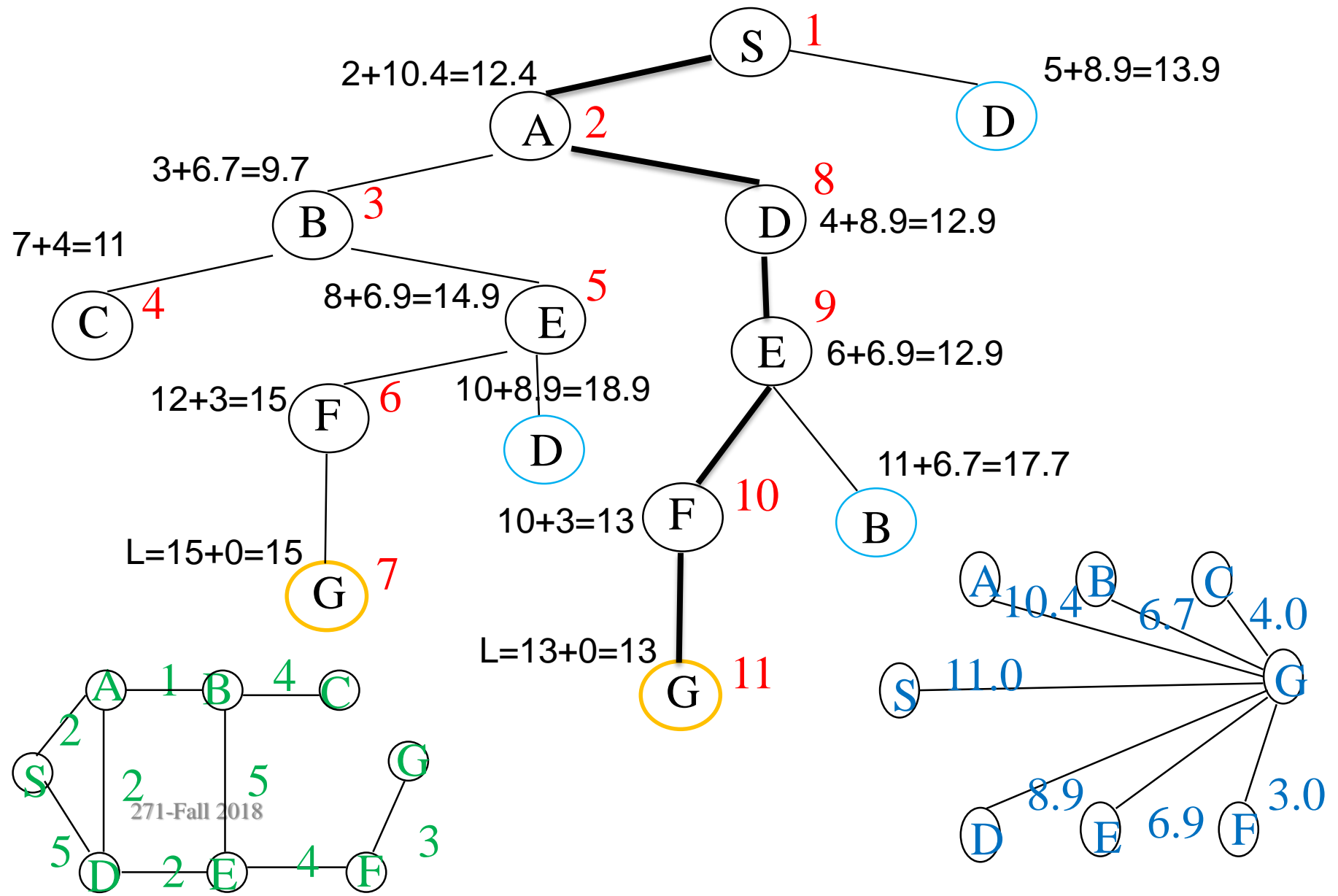
# Search Problem



# Example of A\* Algorithm in Action

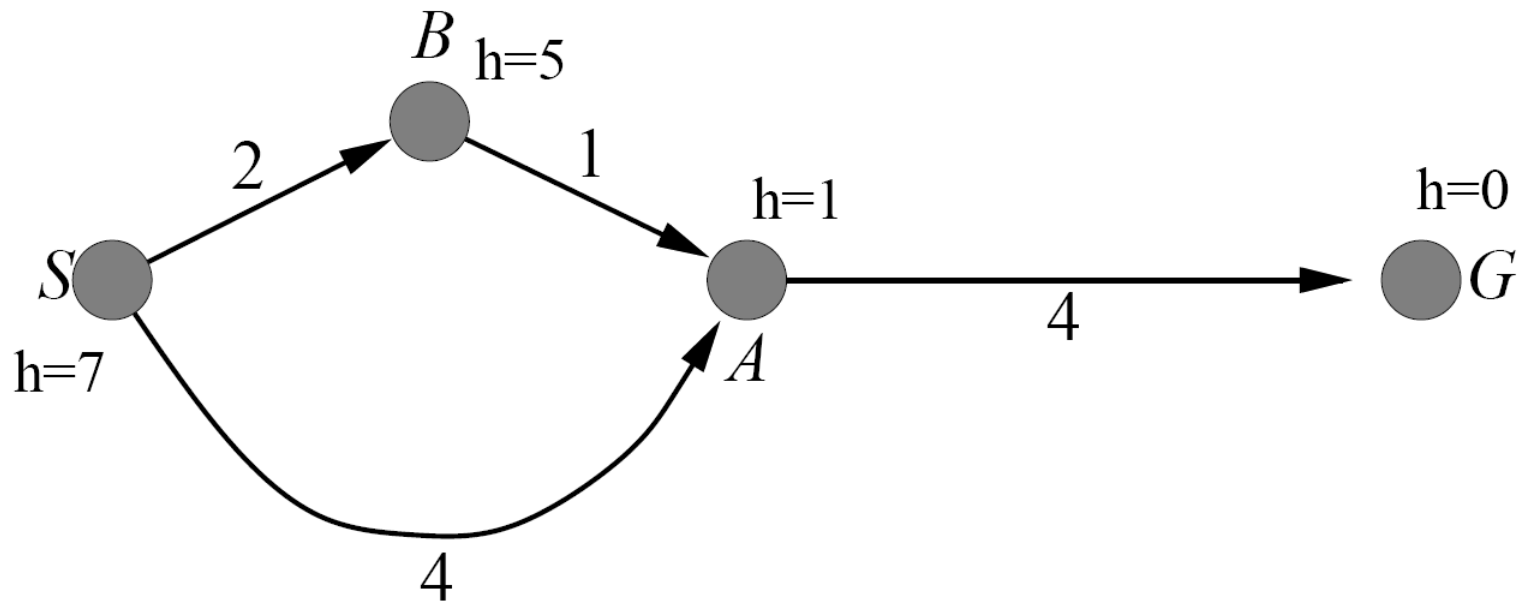


# Example of Branch and Bound in action





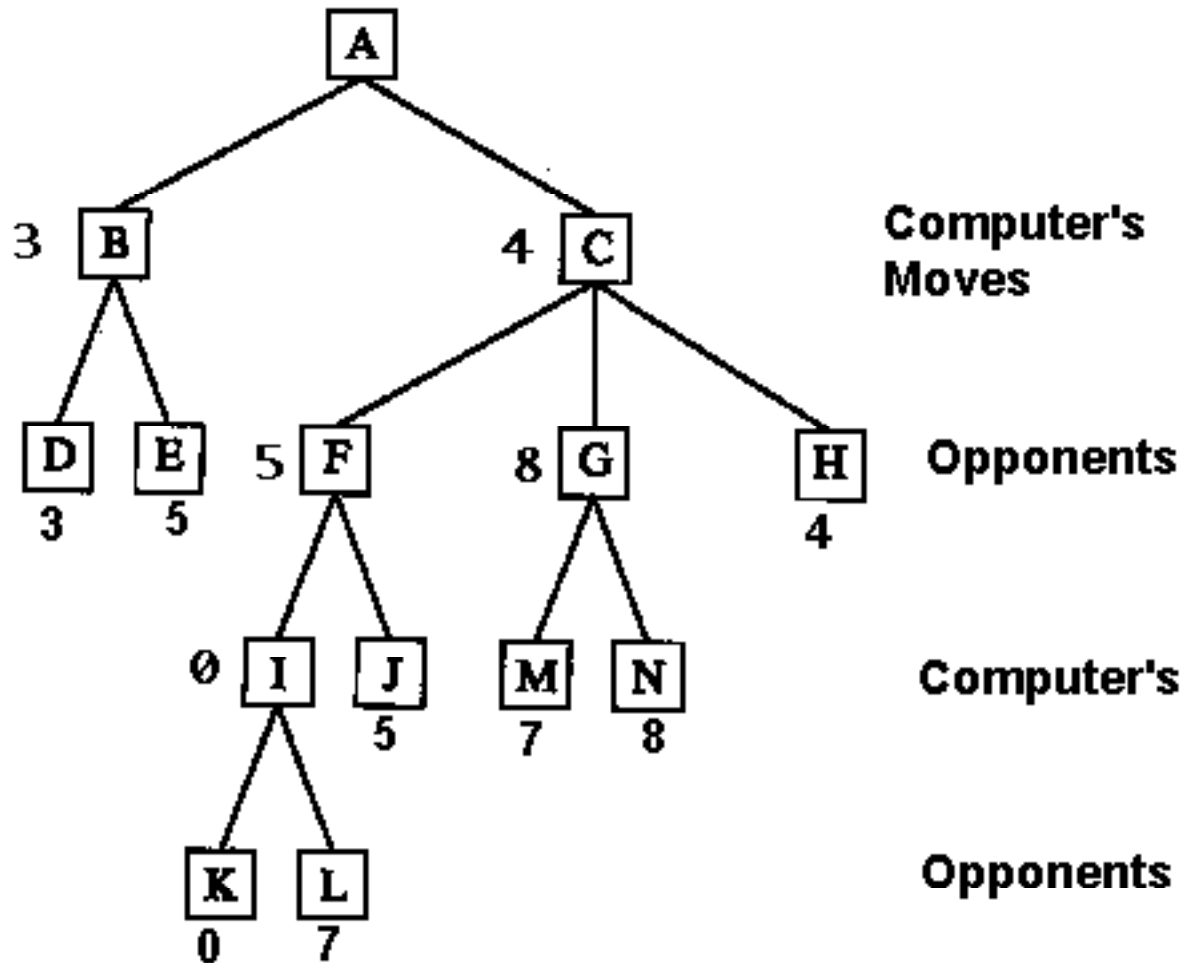
# Admissible but not consistent



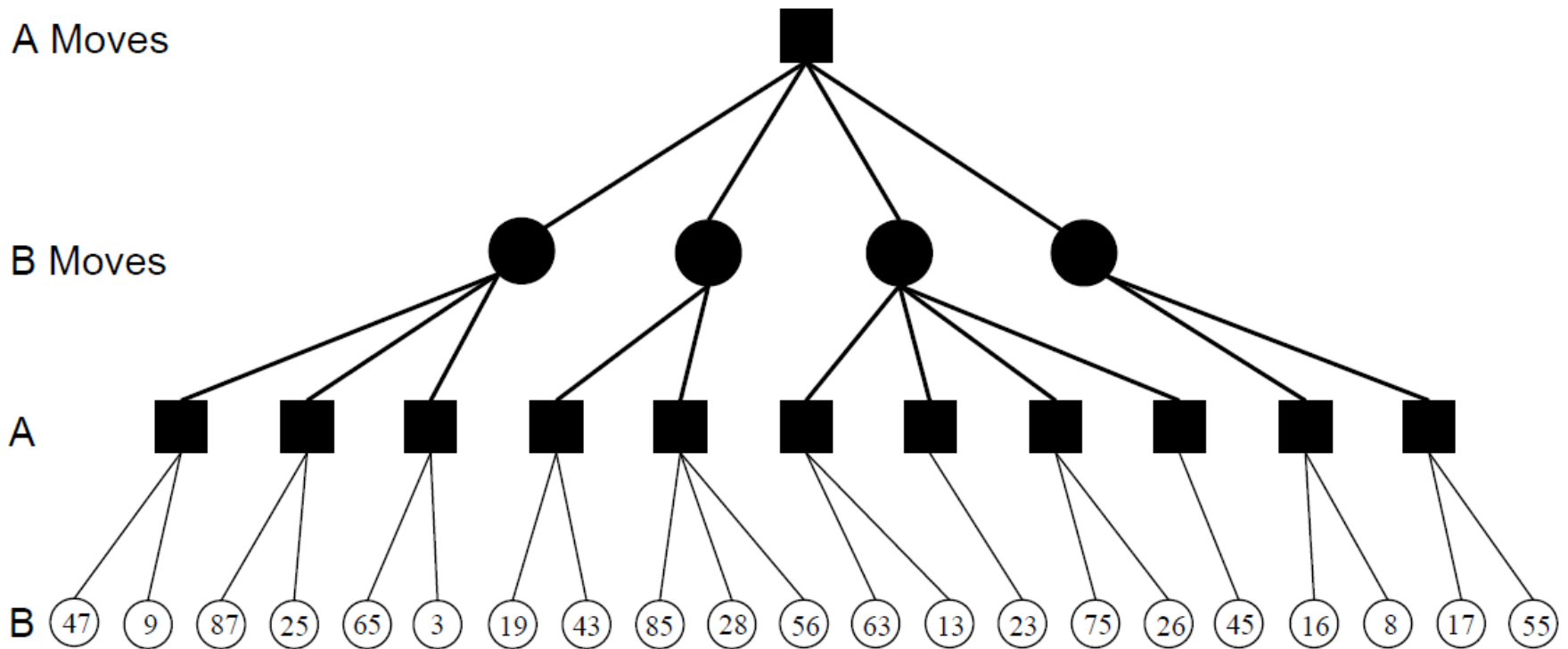
# Chapter 5 (Games) Concepts

- Game tree
  - Players
  - Actions/moves
  - Terminal utility
  - MIN/MAX nodes
- MINIMAX algorithm
- Alpha/Beta pruning
  - Effect of node/move ordering on pruning
- Evaluation functions
  - Why do we need them?
- Stochastic games

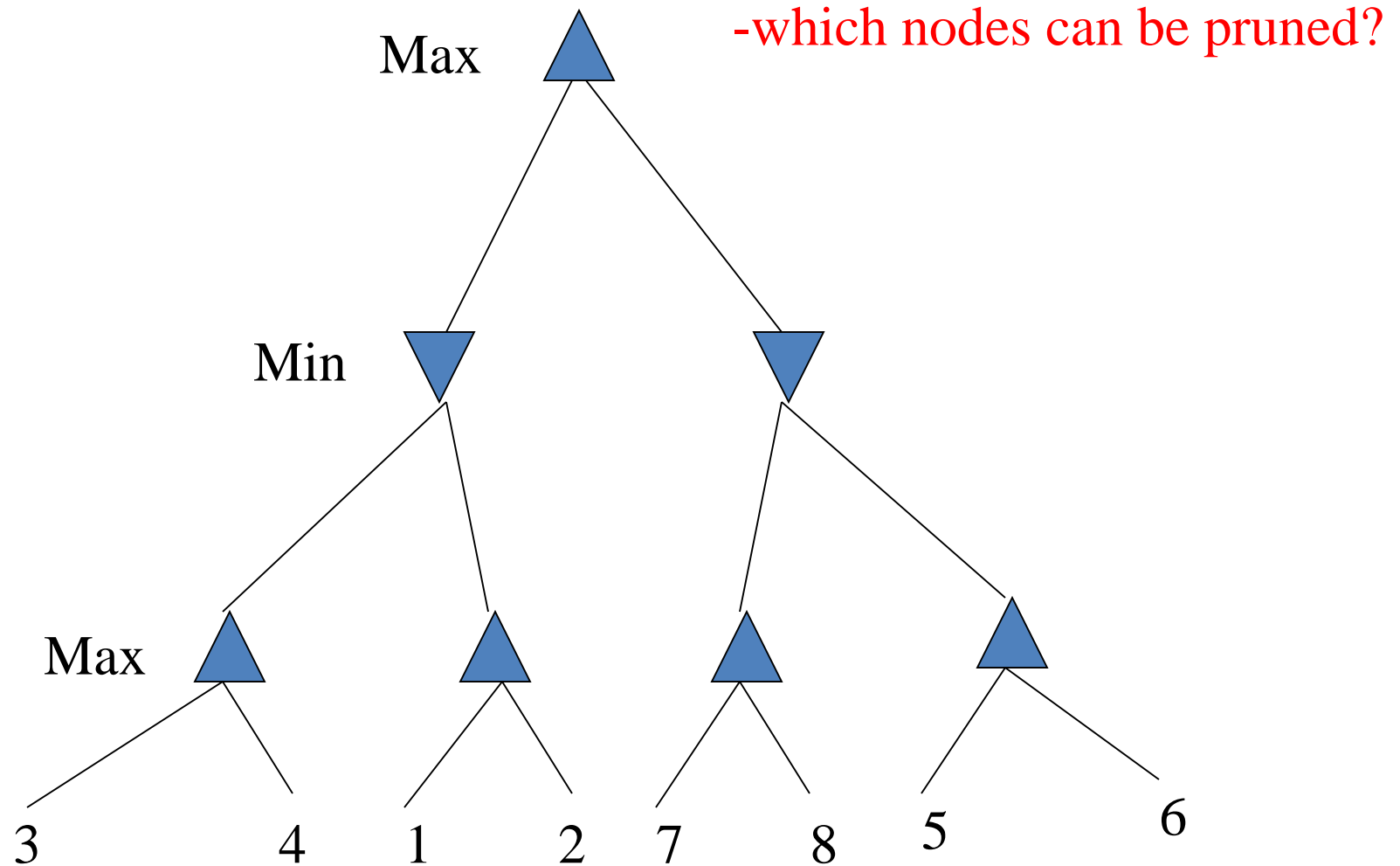
# A Game tree



# Another game tree



# Answer to Example

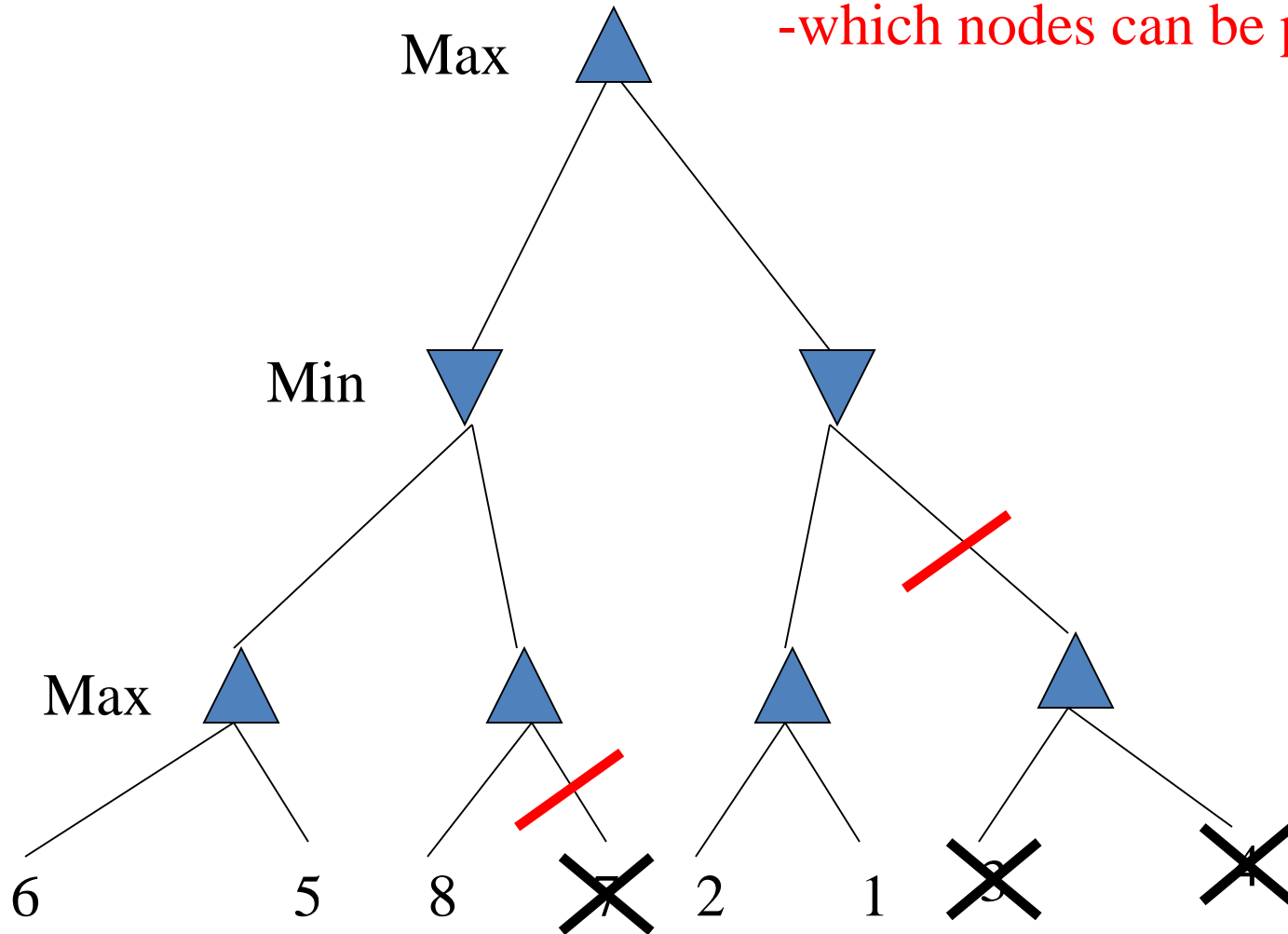


Answer: **NONE!** Because the most favorable nodes for both are explored **last** (i.e., in the diagram, are on the right-hand side).

# Answer to Second Example

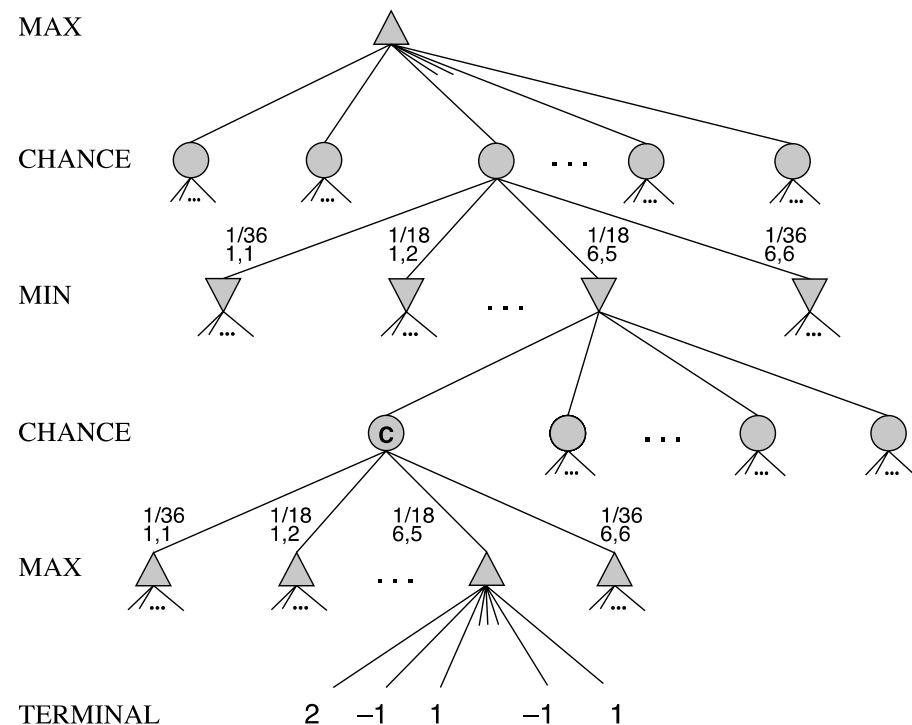
(the exact mirror image of the first example)

-which nodes can be pruned?



Answer: **LOTS!** Because the most favorable nodes for both are explored **first** (i.e., in the diagram, are on the left-hand side).

# Schematic Game Tree for Backgammon Position



- How do we evaluate good move?
- By expected utility leading to expected minimax
- Utility for max is highest expected value of child nodes
- Utility of min-nodes is the lowest expected value of child nodes
- Chance node take the expected value of their child nodes.
- Try Monte-Carlo here!!!

# Chapter 6 (CSP) Concepts

- Language : variables, domains, constraints
  - a solution : assignment of values to variables so that all constraints are satisfied
- Constraint graph
- Local consistency
  - Arc-consistency, path-consistency, k-consistency
- Backtracking search
  - (Q : how is BT search different from DFS?)
  - Variable, value ordering heuristics
- Interleaving search and inference
  - E.g. BT with arc-consistency
- Greedy local search
  - Min-conflicts



# Arc-consistency

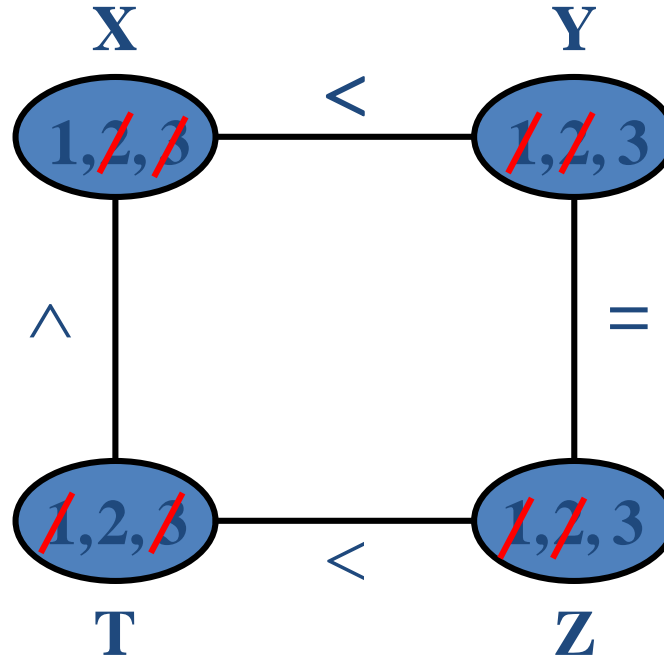
$1 \leq X, Y, Z, T \leq 3$

$X < Y$

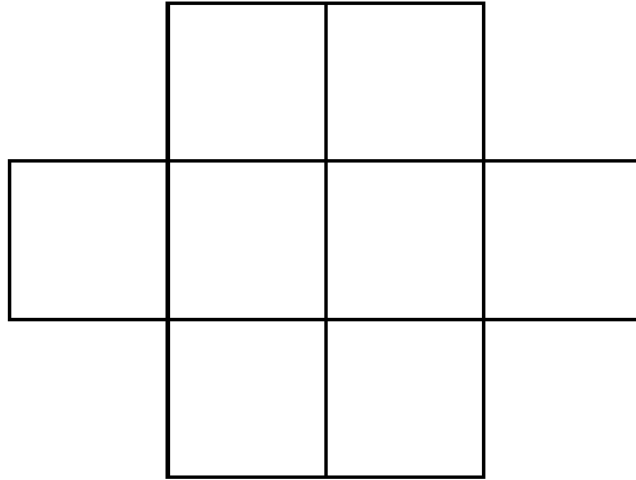
$Y = Z$

$T < Z$

$X < T$



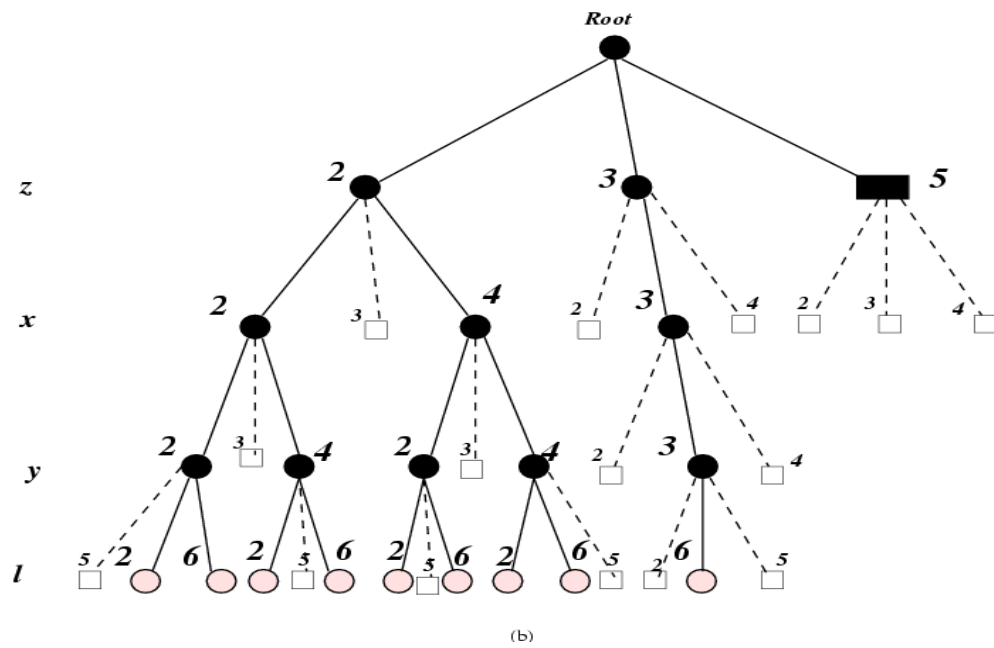
# A Constraint problem



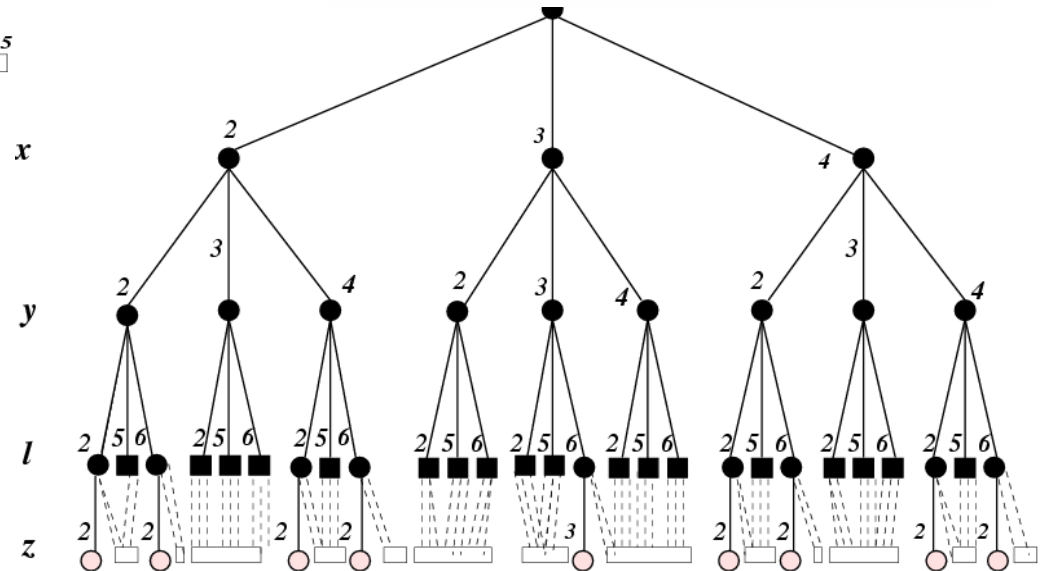
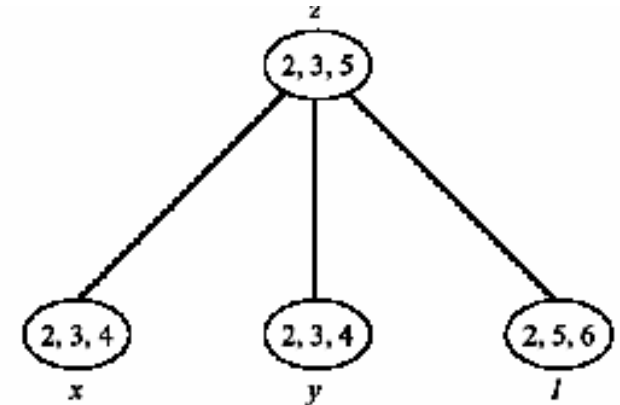
The task is to label the boxes above with the numbers 1-8 such that the labels of any pair of adjacent squares (i.e. horizontal vertical or diagonal) differ by at least 2 (i.e. 2 or more).

- (a) Write the constraints in a relational form and draw the constraint graph.
- (b) Is the network arc-consistent ? if not, compute the arc-consistent network.
- (c) Is the network consistent ? If yes, give a solution.

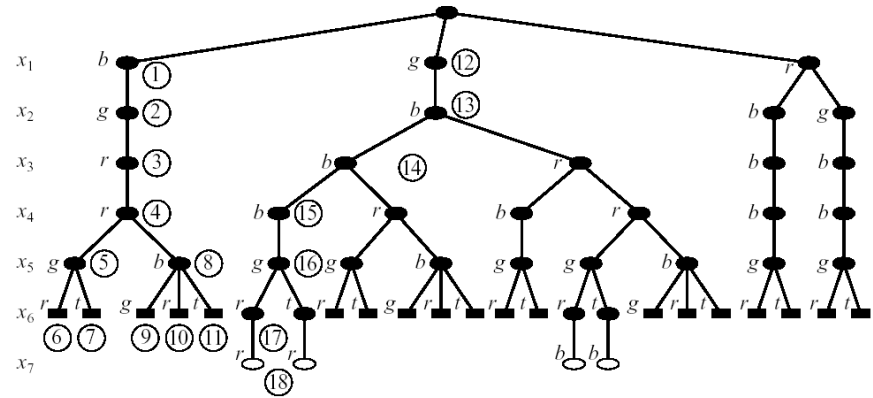
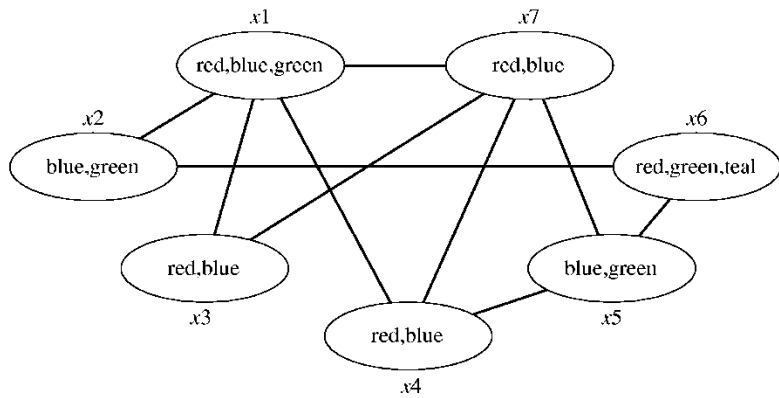
# The effect of variable ordering



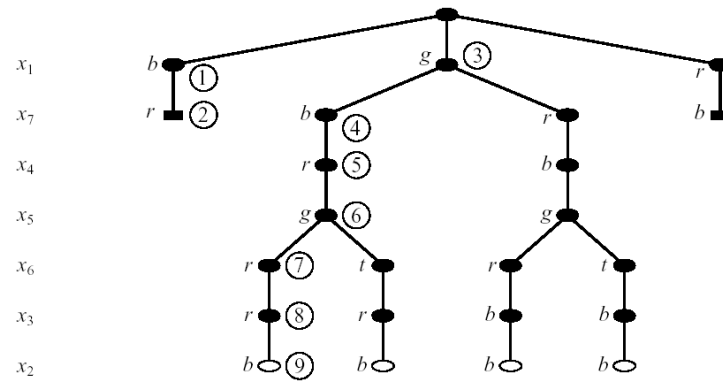
z divides x, y and t



# Backtracking Search for a Solution



(a)



(b)

# Min-Conflicts

	1	2	3	4
$X_1$			Q	
$X_2$	Q			
$X_3$				Q
$X_4$		Q		

At each step, find globally minimizing move!

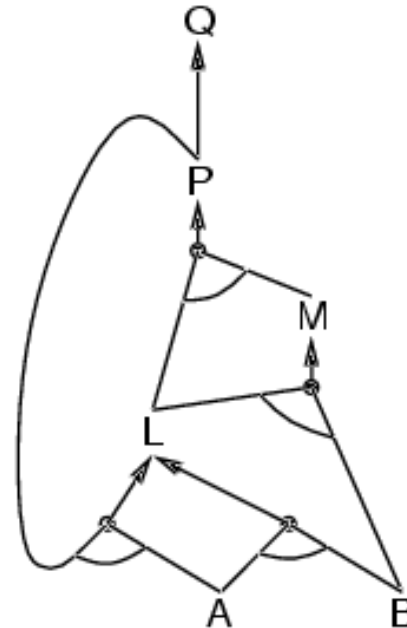
# Chapter 7 (Prop Logic) Concepts

- Syntax : propositional symbols; logical connectives
- Semantics
  - Worlds, models
  - Entailment
  - Inference
  - Soundness/Completeness
  - Validity/Satisfiability
- Model checking
- Modus Ponens
- CNF
- Horn clauses, Forward/Backward chaining
- Resolution
- DPLL backtracking search

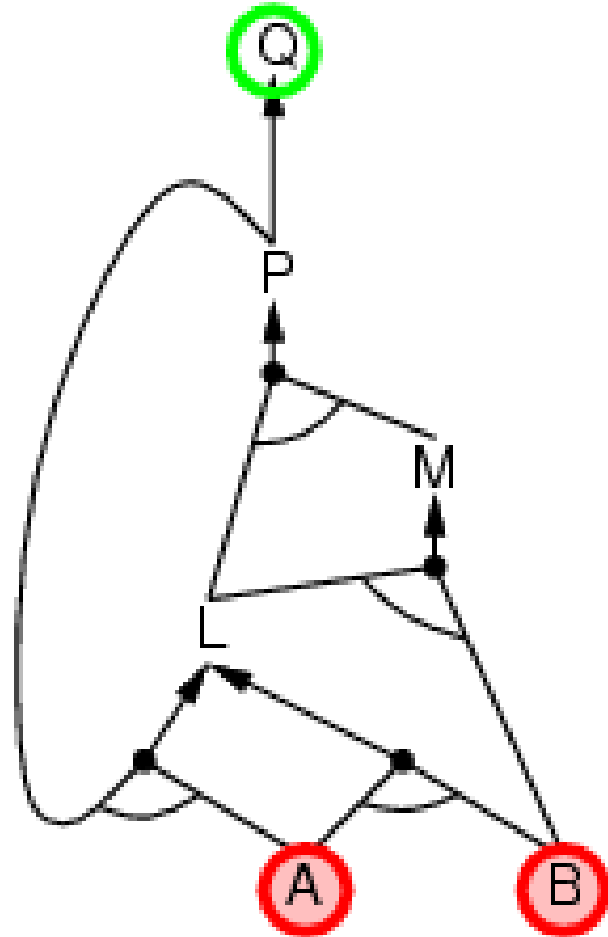
# Forward chaining

- Idea: fire any rule whose premises are satisfied in the *KB*,
  - add its conclusion to the *KB*, until query is found

$P \Rightarrow Q$   
 $L \wedge M \Rightarrow P$   
 $B \wedge L \Rightarrow M$   
 $A \wedge P \Rightarrow L$   
 $A \wedge B \Rightarrow L$   
 $A$   
 $B$



# Backward chaining example



$$P \Rightarrow Q$$

$$L \wedge M \Rightarrow P$$

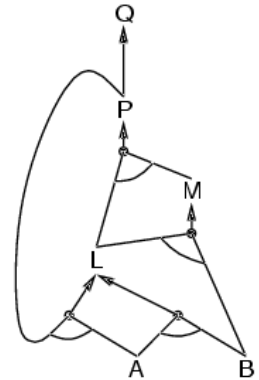
$$B \wedge L \Rightarrow M$$

$$A \wedge P \Rightarrow L$$

$$A \wedge B \Rightarrow L$$

$$A$$

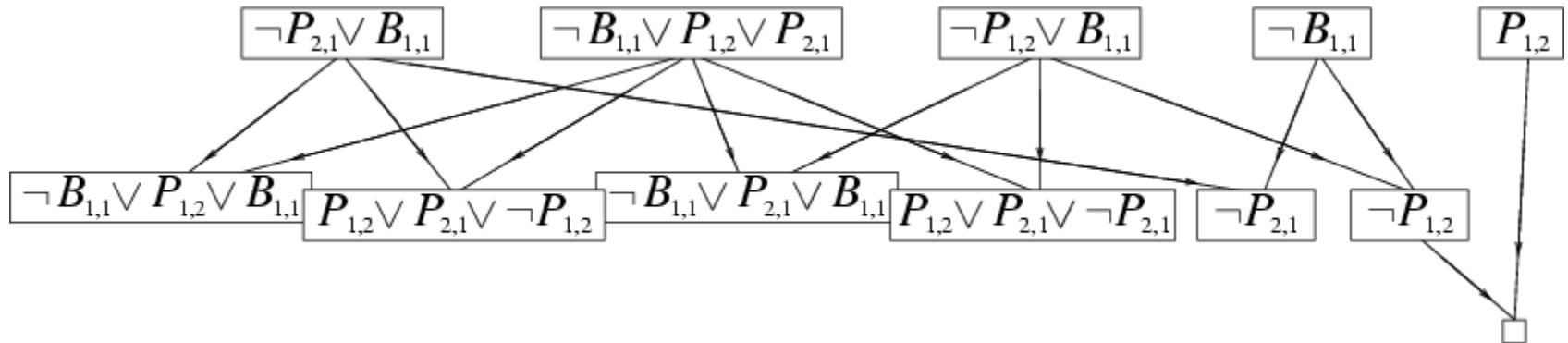
$$B$$





# Resolution example

- $KB = (B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})) \wedge \neg B_{1,1}$ ,  $\alpha = \neg P_{1,2}$
- Convert KB/neg-query to CNF



# Chapters 8,9 (FOL) Language

- Syntax
  - Variables, const symbols, fn symbols, predicate symbols
  - Terms, atomic sentences
  - Quantifiers
- Semantics
  - Model, interpretation
  - Entailment

# Chapters 8,9 (FOL) Inference

- Universal, existential instantiation
- Unification
- Generalized Modus Ponens
  - Definite clauses
- Converting a FOL sentence to CNF
- Inference algorithms
  - Forward Chaining
  - Backward Chaining
  - Resolution (answer extraction)

# FOL Resolution Problem

(Problem 16.10 from Nilsson) Use resolution refutation on a set of clauses to prove that there is a green object if we are given:

- If pushable objects are blue, then nonpushable ones are green.
  - All objects are either blue or green but not both.
  - If there is a nonpushable object, then all pushable ones are blue.
  - Object 01 is pushable.
  - Object 02 is not pushable.
- (a) Convert these statements to expressions in first-order predicate calculus.
  - (b) Convert the preceding predicate-calculus expressions to clause form.
  - (c) Combine the preceding clause form expressions with the clause form of the negation of the statement to be proved, and then show the steps used in obtaining a resolution refutation
  - (d) Use resolution-answer-extraction to find a particular object that is green

# Chapter 10 (Planning) Concepts

- STRIPS (PDDL) language
  - Factored representation of states
  - Actions (schema) : PreCondition, Effects lists
- Planning as Forward/Backward search
- Heuristics for planning, relaxed problem idea
  - Ignore PC, neg effects, etc.
  - Abstraction
- Planning graphs : construction, properties
  - Using planning graphs for heuristic computation
- Planning as satisfiability

# STRIPS/PDDL

```
Init(On(A, Table) ∧ On(B, Table) ∧ On(C, Table)
    ∧ Block(A) ∧ Block(B) ∧ Block(C)
    ∧ Clear(A) ∧ Clear(B) ∧ Clear(C))
Goal(On(A, B) ∧ On(B, C))
Action(Move(b, x, y),
    PRECOND: On(b, x) ∧ Clear(b) ∧ Clear(y) ∧ Block(b) ∧
        {b ≠ x} ∧ {b ≠ y} ∧ {x ≠ y},
    EFFECT: On(b, y) ∧ Clear(x) ∧ ¬ On(b, x) ∧ ¬ Clear(y))
Action(MoveToTable(b, x),
    PRECOND: On(b, x) ∧ Clear(b) ∧ Block(b) ∧ {b ≠ x},
    EFFECT: On(b, Table) ∧ Clear(x) ∧ ¬ On(b, x))
```

**Figure 11.4** A planning problem in the blocks world: building a three-block tower. One solution is the sequence  $[Move(B, Table, C), Move(A, Table, B)]$ .

# Planning as Satisfiability

- Propositionalize actions
- Define initial state ( $F/\neg F$  for everything given/unknown)
- Pick plan length  $K$
- Propositionalize the goal; assert goal at time  $k+1$
- Add precondition/effect axioms
  - $A^k \rightarrow \text{Preconditions}(A^k) \wedge \text{Effects}(A^{k+1})$
- Add successor-state axioms; for each fluent  $F$ 
  - $\neg F^k \wedge F^{k+1} \rightarrow \text{ActionCauses}F^{k+1}$
- Add action exclusion axioms
  - Exactly one action at a time (can have NoOP)